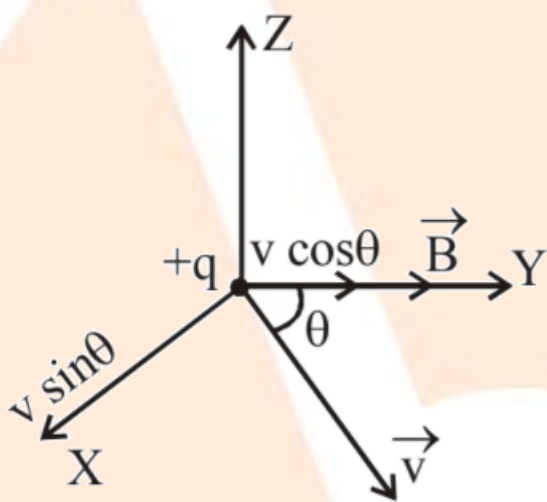


Revision Notes

Class - 12 Physics

Chapter 4 - Moving Charges And Magnetism

1. **Force on a moving charge:-**The source of magnetic field is a moving charge.



Suppose a positive charge q is in motion in a uniform magnetic field \vec{B} with velocity \vec{v} .

n

$$\therefore F \propto qBv \sin \theta \Rightarrow F = kqBv \sin \theta \quad [k = \text{constant}]$$

Where in S.I. system, $k = 1$

$$\therefore F = qBv \sin \theta \text{ and } \vec{F} = q \left(\vec{v} \times \vec{B} \right)$$

2. **Magnetic field strength $\left(\vec{B} \right)$:**

We can see that in the equation,

$F = qBv \sin \theta$, if $q = 1, v = 1$,

$\sin\theta=1$ i.e. $\theta = 90^\circ$ then $F = B$.

Therefore magnetic field strength can be known as the force felt by a unit charge in motion with unit velocity perpendicular to the direction of magnetic field.

There are some special cases for this:

- (1) If $\theta = 0^\circ$ or 180° , $\sin\theta=0$
 $\therefore F = 0$

A charged particle which is in motion parallel to the magnetic field, will be not experiencing any force.

- (2) When $v = 0, F = 0$

At rest, a charged particle in a magnetic field will be not experiencing any force.

- (3) When $\theta = 90^\circ$, $\sin\theta=1$ then the force will be maximum

$$F_{\max} = qvB$$

A charged particle in motion perpendicular to the magnetic field will be experiencing maximum force.

- 3. S.I. unit of magnetic field intensity:** The S.I unit has been found to be tesla (T).

$$B = \frac{F}{qv\sin\theta}$$

When $q = 1C, v = 1m/s, \theta = 90^\circ$ That is, $\sin\theta=1$ and $F=1N$

Then $B = 1T$.

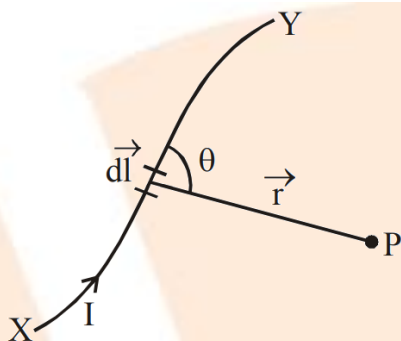
At a point, the strength of magnetic field can be called as 1T if a charge of 1C which have a velocity of 1 m/s while in motion at right angle to a magnetic field experiences a force of 1N at that point.

- 4. Biot-Savart's law:**– The strength of magnetic flux density or magnetic field at a point P (dB) because of the current element dl will be dependent on,

- (i) $dB \propto I$
(ii) $dB \propto dl$

(iii) $dB \propto \sin\theta$

(iv) $dB \propto \frac{1}{r^2}$,



When we combine them, $dB \propto \frac{Idl \sin\theta}{r^2} \Rightarrow dB = k \frac{Idl \sin\theta}{r^2}$ [k =

Proportionality constant]

In S.I. units, $k = \frac{\mu_0}{4\pi}$ where μ_0 can be called as permeability of free space.

$$\mu_0 = 4\pi \times 10^{-7} \text{ TA}^{-1}\text{m}$$

$$\therefore dB = \frac{\mu_0}{4\pi} \frac{Idl \sin\theta}{r^2} \text{ and } \vec{dB} = \frac{\mu_0}{4\pi} I \frac{(\vec{dl} \times \vec{r})}{r^3}$$

\vec{dB} will be perpendicular to the plane containing \vec{dl} and \vec{r} and will be directed inwards.

5. Applications of Biot-Savart's law:–

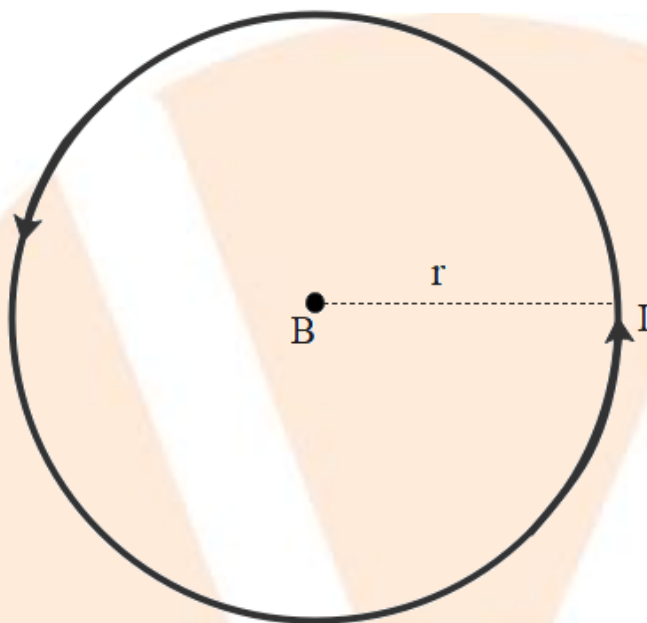
- Magnetic field (B) kept at the Centre of a Current Carrying Circular Coil of radius r .

$$B = \frac{\mu_0 I}{2r}$$

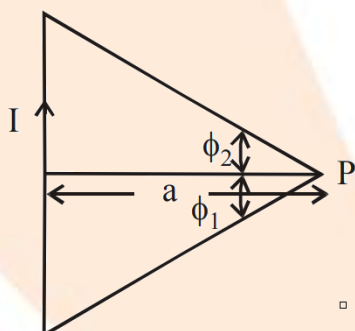
If there are n turns, then the magnetic field at the centre of a circular coil of n turns will be,

$$B = \frac{\mu_0 n I}{2r}$$

Here n will be the number of turns of the coil. I will be the current in the coil and r will be the radius of the coil.



- Magnetic field because of a straight conductor carrying current.

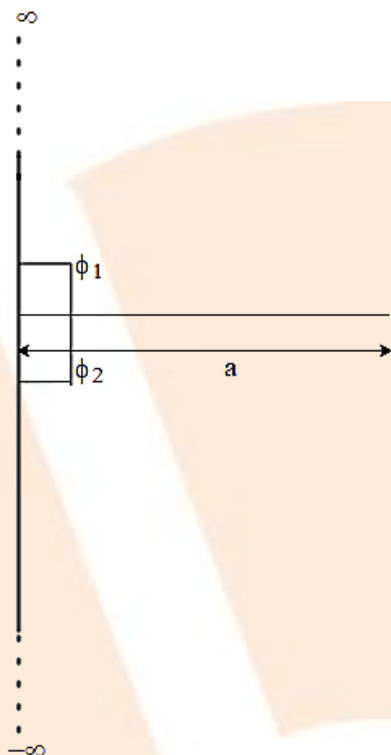


$$B = \frac{\mu_0 I}{4\pi a} (\sin \phi_2 + \sin \phi_1)$$

Here a will be the perpendicular distance of the conductor from the point where the field is to be measured.

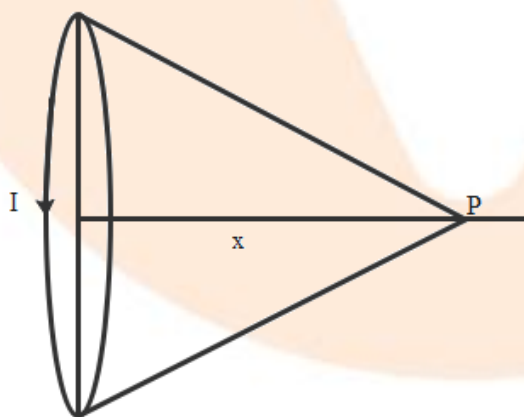
ϕ_1 and ϕ_2 will be the angles created by the two ends of the conductor with the point. In case of an infinitely long conductor, $\phi_1 = \phi_2 = \frac{\pi}{2}$

$$\therefore B = \frac{\mu_0}{4\pi} \cdot \frac{2I}{a}$$



- At a point on the axis, magnetic field of a Circular Coil Carrying Current.

If point P is lying far away from the centre of the coil.



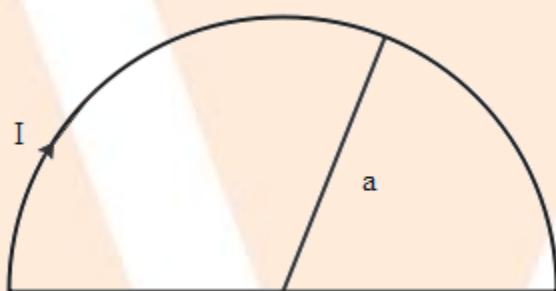
$$B = \frac{\mu_0}{4\pi} \frac{2M}{x^3}$$

Where $M = nIA =$ magnetic dipole moment of the coil. x be the distance of the point where the field is needed to be measured, n be the number of turns, I

be the current and A be the area of the coil.

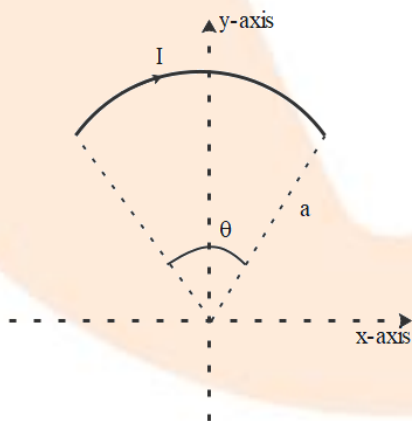
- Magnetic field at the centre of a semi-circular current-carrying conductor will be,

$$B = \frac{\mu_0 I}{4a}$$



- Magnetic field at the centre of an arc of circular current-carrying conductor which is subtending an angle θ at the centre will be,

$$B = \frac{\mu_0 I \theta}{4 \pi a}$$

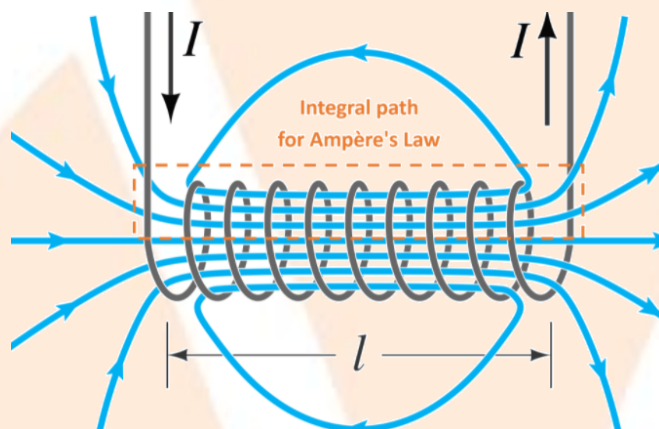


6. Ampere's circuital law:–

Around any closed path in vacuum line integral of magnetic field \vec{B} will be μ_0 times the total current through the closed path. that is, $\oint \vec{B} \cdot d\vec{l} = \mu_0 I$

7. Application of Ampere's circuital law:-

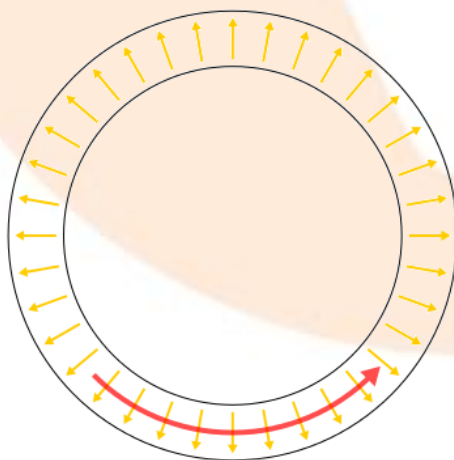
(a) Magnetic field because of a current carrying solenoid, $B = \mu_0 n I$



n be the number of turns per unit length of the solenoid.

In the edge portion of a short solenoid, $B = \frac{\mu_0 n I}{2}$

(b) Magnetic field because of a toroid or endless solenoid



Top view

$$B = \mu_0 n I$$

8. Motion in uniform electric field of a charged particle:–

Parabola is the path of a charged particle in an electric field.

$$\text{Equation of the parabola be } x^2 = \frac{2mv^2}{qE} y$$

Where x be the width of the electric field.

y be the displacement of the particle from its straight path.

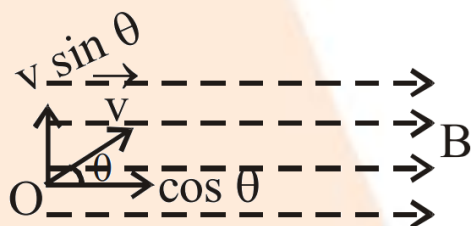
v be the speed of the charged particle.

q be the charge of the particle

E be the electric field intensity.

m be the mass of the particle.

- 9.** In a magnetic field (\vec{B}) which is uniform, the path of a particle which is charged in motion with a velocity \vec{v} creating an angle θ with \vec{B} will be a helix.



The component of velocity $v \cos \theta$ will not be given a force to the charged particle, hence under this velocity in the direction of \vec{B} , the particle will move forward with a fixed velocity. The other component $v \sin \theta$ will create the force $F = qBv \sin \theta$, which will be supplying the needed centripetal force to the charged particle in the motion along a circular path having radius r .

$$\therefore \text{Centripetal force} = \frac{m(v \sin \theta)^2}{r} = Bqv \sin \theta$$

$$\therefore v \sin \theta = \frac{Bqr}{m}$$

$$\text{Angular velocity of rotation} = \omega = \frac{v \sin \theta}{r} = \frac{Bq}{m}$$

$$\text{Frequency of rotation} = \nu = \frac{\omega}{2\pi} = \frac{Bq}{2\pi m}$$

$$\text{Time period of revolution} = T = \frac{1}{\nu} = \frac{2\pi m}{Bq}$$

10. Cyclotron: This can be defined as a device we use for accelerating and therefore energize the positively charged particle. This can be created by keeping the particle, in an oscillating perpendicular magnetic field and a electric field. The particle will be moving in a circular path.

\therefore Centripetal force = magnetic Lorentz force

$$\Rightarrow \frac{mv^2}{r} = Bqv \Rightarrow \frac{mv}{Bq} = r \leftarrow \text{radius of the circular path}$$

$$\text{Time for travelling a semicircular path} = \frac{\pi r}{v} = \frac{\pi m}{Bq} = \text{constant} .$$

When v_0 be the maximum velocity of the particle and r_0 be the maximum radius of its path then we can say that,

$$\frac{mv_0^2}{r_0} = Bqv_0 \Rightarrow v_0 = \frac{Bqr_0}{m}$$

Maximum kinetic energy of the particle

$$= \frac{1}{2} mv_0^2 = \frac{1}{2} m \left(\frac{Bqr_0}{m} \right)^2 \Rightarrow (\text{K.E.})_{\text{max.}} = \frac{B^2 q^2 r_0^2}{2m}$$

$$\text{Time period of the oscillating electric field} \Rightarrow T = \frac{2\pi m}{Bq} .$$

Time period be the independent of the speed and radius.

$$\text{Cyclotron frequency} = \nu = \frac{1}{T} = \frac{Bq}{2\pi m}$$

$$\text{Cyclotron angular frequency} = \omega_0 = 2\pi\nu = \frac{Bq}{m}$$

11. Force acting on a current carrying conductor kept in a magnetic field will be,

$$\vec{F} = I \left| \vec{l} \times \vec{B} \right| \text{ or } F = I l B \sin \theta$$

Here I be the current through the conductor

B be the magnetic field intensity.

l be the length of the conductor.

θ be the angle between the direction of current and magnetic field.

(i) If $\theta = 0^\circ$ or 180° , $\sin \theta \Rightarrow 0 \Rightarrow F = 0$

\therefore If a conductor is kept along the magnetic field, no force will be acting on the conductor.

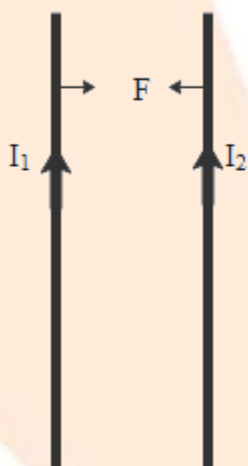
(ii) If $\theta = 90^\circ$, $\sin \theta = 1$, F will be maximum.

$$F_{\max} = I l B$$

If the conductor has been kept normal to the magnetic field, it will be experiencing maximum force.

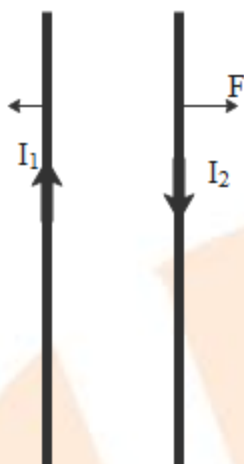
12. Force between two parallel current carrying conductors:–

(a) If the current will be in similar direction the two conductors will be attracting each other with a force



$$F = \frac{\mu_0}{4\pi} \cdot \frac{2I_1 I_2}{r} \text{ per unit length of the conductor}$$

(b) If the current is in opposite direction the two conductors will be repelling each other with an equal force.



(c) S.I. unit of current is 1 ampere. (A).

1A can be defined as the current which on flowing through each of the two parallel uniform linear conductor kept in free space at a distance of 1m from each other creates a force of 2×10^{-7} N/m along their lengths.

13. Torque experienced on a current carrying coil kept in a magnetic field:–

$\vec{\tau} = \vec{M} \times \vec{B} \Rightarrow \tau = MB \sin \alpha = nIBA \sin \alpha$ where M be the magnetic dipole moment of the coil.

$$M = nIA$$

Where n be the number of turns of the coil.

I be the current through the coil.

B be the intensity of the magnetic field.

A be the area of the coil.

α will be the angle in between the magnetic field $\left(\vec{B} \right)$ and normal to the plane of the coil.

Special Cases will be:

(i) When the coil has been kept parallel to magnetic field $\theta = 0^\circ$,
 $\cos \theta = 1$ then torque will be maximum.

$$\tau_{\max} = nIBA$$

(ii) When the coil is kept perpendicular to magnetic field, $\theta = 90^\circ$,

$$\cos \theta = 0$$

$$\therefore \tau = 0$$

- 14. Moving coil galvanometer:** – This has been on the basis on the principle that if a coil carrying current has been kept in a magnetic field it is experiencing a torque. There is a restoring torque because of the phosphor bronze strip which is bringing back the coil to its normal position.

In equilibrium,

Deflecting torque = Restoring torque

$$nIBA = k\theta \quad [k = \text{restoring torque/unit twist of the phosphor bronze strip}]$$

$$I = \frac{k}{nBA} \theta = G\theta \quad \text{where } G = \frac{k}{nBA} = \text{Galvanometer constant}$$

$$\therefore I \propto \theta$$

Current sensitivity of the galvanometer can be defined as the deflection made if the unit current has been passed through the galvanometer.

$$I_s = \frac{\theta}{I} = \frac{nBA}{k}$$

Voltage sensitivity can be explained as the deflection created if unit potential difference has been applied across the galvanometer.

$$V_s = \frac{\theta}{V} = \frac{\theta}{IR} = \frac{nBA}{kR} \quad [R = \text{Resistance of the galvanometer}]$$

- 15. The maximum sensitivity of the galvanometer is having some conditions:-**
The galvanometer has been defined to be sensitive if a small current develops a large deflection.

$$\therefore \theta = \frac{nBA}{k} I$$

$\therefore \theta$ will be large if (i) n is large, (ii) B is large (iii) A is large and (iv) k is small.

- 16. Conversion of galvanometer into voltmeter and ammeter**

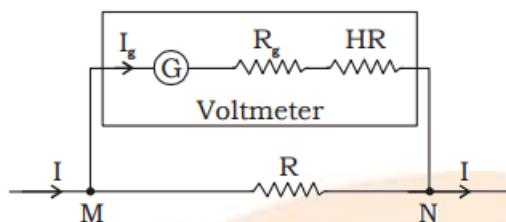
(a) A galvanometer has been converted to voltmeter by putting a high resistance in series with it.

Total resistance of voltmeter = $R_g + R$ where R_g be the galvanometer resistance.

R be the resistance added in series.

$$\text{Current through the galvanometer} = I_g = \frac{V}{R_g + R}$$

Here V is the potential difference across the voltmeter.

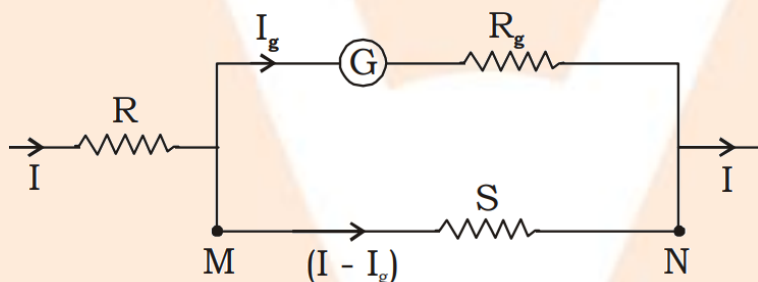


$$\therefore R = \frac{V}{I_g} - G$$

Range of the voltmeter: $0 - V$ volt.

(b) A galvanometer can be converted into an ammeter by the connection of a low resistance in parallel with it (shunt)

Shunt = $S = \left(\frac{I_g}{I - I_g} \right) R_g$ where R_g be the galvanometer's resistance.



I be the total current through the ammeter.

I_g be the current through the ammeter.

Effective resistance of the ammeter will be,

$$R = \frac{R_g}{R_g + S}$$

The range of the ammeter will be $0 - IA$. An ideal ammeter will be having zero resistance.